

الجامعة السورية الخاصة SYRIAN PRIVATE UNIVERSITY

كلية هندسة الحاسوب والمعلوماتية **Computer and Informatics Engineering** Faculty

# **Electric Circuits I**

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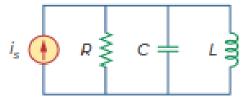
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# Chapter 8 Second-Order Circuits

8.1 Examples of 2nd order RCL circuit
8.2 Finding Initial and Final Values
8.3 The source-free series RLC circuit
8.4 The source-free parallel RLC circuit
8.5 Step response of a series RLC circuit
8.6 Step response of a parallel RLC

## 8.1 Examples of 2nd order RCL circuit

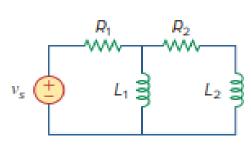
- A second-order circuit is characterized by a secondorder differential equation. It consists of resistors and the equivalent of two energy storage elements.
- Typical examples of second-order circuits:
  - (a) series RLC circuit,
  - (b) parallel RLC circuit,
  - (c) RL circuit,
  - (d) RC circuit.



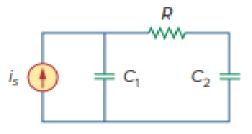
(b)

(a)

C.







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(d)

## **8.2 Finding Initial and Final Values**

- The major problem in analysis of the second-order circuits is finding the initial and final conditions on circuit variables: v(0), i(0), dv(0)/dt, di(0)/dt,  $i(\infty)$ , and  $v(\infty)$ .
- There are **two key points** to keep in mind in determining the initial conditions.
  - First—we must carefully handle the polarity of voltage *v*(*t*) across the capacitor and the direction of the current *i*(*t*) through the inductor.
  - Second, keep in mind that the capacitor voltage is always *continuous* so that  $v(0^+) = v(0^-)$

and the inductor current is always *continuous* so that  $i(0^+) = i(0^-)$ where  $t = 0^-$  denotes the time just **before** a switching event and  $t = 0^+$  is the time just **after** the switching event, assuming that the switching event takes place at t = 0.

**Example 8.1.** The switch in Fig. has been closed for a long time. It is open at t = 0. Find:  $i(0^+)$ ,  $v(0^+)$ ,  $di(0^+)/dt$ ,  $dv(0^+)/dt$ ,  $i(\infty)$ ,  $v(\infty)$ .

12 V

### Solution:

a) If the switch is closed a long time before

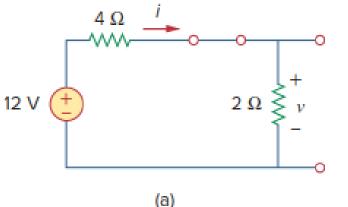
t = 0, it means that the circuit has reached dc steady state at t = 0.

At dc steady state, the inductor acts like a short circuit, while the capacitor acts like an open circuit, so we have the circuit in Fig.(a) at t = 0-. Thus,

$$i(0^{-}) = \frac{12}{4+2} = 2A, \quad v(0^{-}) = 2i(0^{-}) = 4V$$

As the inductor current and the capacitor voltage cannot change abruptly,

$$i(0^+) = i(0^-) = 2A, \quad v(0^+) = v(0^-) = 4V$$



0.25 H

2Ω

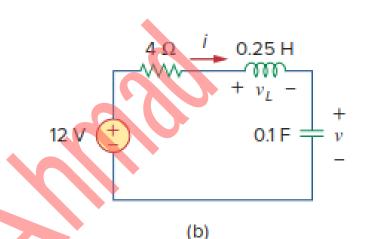
t = 0

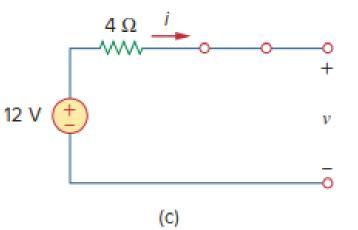
0.1 F

0.25 H 4Ω b) At t = 0+, the switch is open; Fig.(b). The same current flows through both the 2Ω 12 V 0.1 F inductor and capacitor. t = 0Hence,  $i_{C}(0^{+}) = i(0^{+}) = 2A$  $i_{C} = C \frac{dv}{dt} \Leftrightarrow \frac{dv}{dt} = \frac{i_{C}}{C} \Rightarrow \frac{dv(0^{+})}{dt} = \frac{i_{C}(0^{+})}{C} = \frac{2}{0.1} = 20 \text{ V/s}$ 4Ω \_ 0.25 H Similarly,  $v_L = L \frac{di}{dt} \Leftrightarrow \frac{di}{dt} = \frac{v_L}{L}$ 12 V 0.1 F Applying KVL to the loop: (b)  $-12 + 4i(0^+) + v_L(0^+) + v(0^+) = 0$  $\Rightarrow v_L(0^+) = 12 - 8 - 4 = 0$  $\Rightarrow \frac{di(0^+)}{dt} = \frac{v_L(0^+)}{L} = \frac{0}{0.25} = 0 \text{ A/s}$ 9/23/2018 Dr. Eng. Hassan Ahmad 6 c) For t > 0, the circuit undergoes transience. But as  $t \rightarrow \infty$ , the circuit reaches steady state again.

The inductor acts like a short circuit and the capacitor like an open circuit, so that the circuit in Fig.(b) becomes that shown in Fig. (c), from which we have

 $i(\infty) = 0$  A,  $v(\infty) = 12$  V





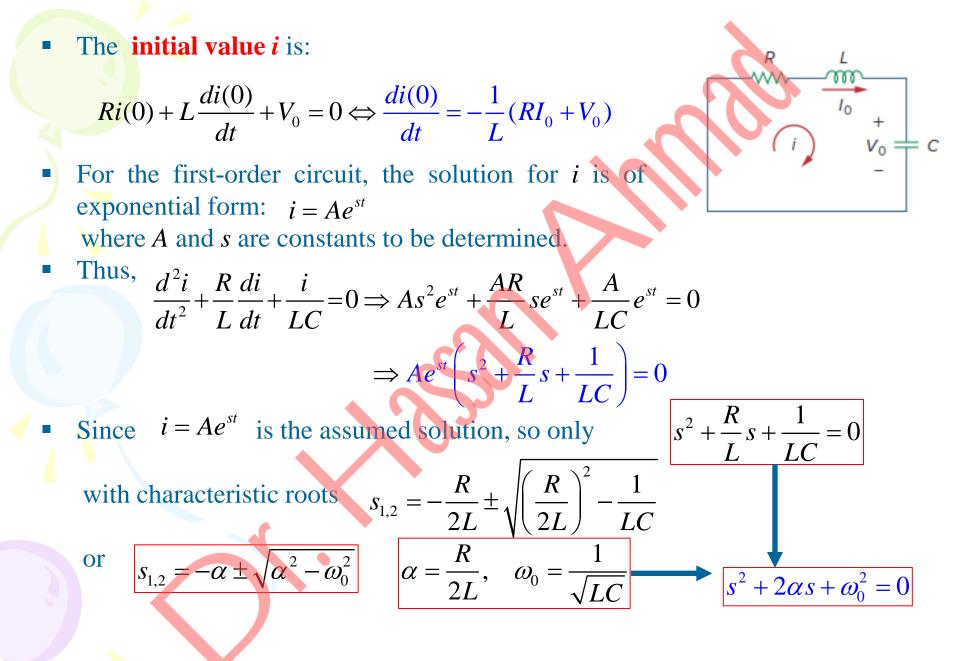
## 8.3 The Source-Free Series RLC Circuits

- The solution of the source-free series *RLC* circuit is called as the **natural response** of the circuit.
- The circuit is excited by the energy initially stored in the capacitor  $(V_0)$  and inductor  $(I_0)$ .
  - Thus, at t = 0,  $v(0) = \frac{1}{C} \int_{-\infty}^{0} i dt = V_0$ ,  $i(0) = I_0$
  - Applying KVL around the loop:
  - By differentiate with respect to t, we get

$$\frac{d^2i}{dt^2} + \frac{R}{L}\frac{di}{dt} + \frac{i}{LC} = 0$$

 $Ri + L\frac{di}{dt} + \frac{1}{C}\int_{-\infty}^{0}i(\tau)d\tau = 0$ 

• This is a second-order differential equation.



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• The two values of *s* indicate that there are two possible solutions for *i*,

$$i_1 = A_1 e^{s_1 t}, \quad i_2 = A_2 e^{s_2 t} \Longrightarrow i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

Sot

where the constants  $A_1$  and  $A_2$  are determined from the initial values i(0) and di(0)/dt.

### There are three types of solutions:

1. Overdamped Case (فوق متضائل),

$$\alpha > \omega_0$$
, i.e.  $C > 4L/R^2 \Rightarrow i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$ 

– A typical overdamped response in Fig.(a).

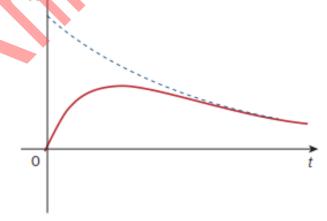
2. Critically Damped Case (متضائل بشکل حرج)

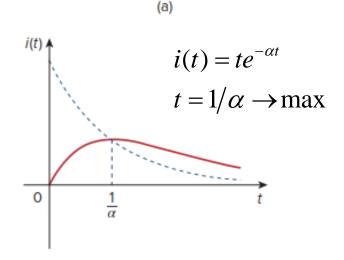
$$\alpha = \omega_0$$
, i.e.  $C = 4L/R^2 \Rightarrow s_1 = s_2 = -\alpha = -\frac{R}{2L}$ 

$$\Rightarrow i(t) = A_1 e^{-\alpha t} + A_2 e^{-\alpha t} = (A_1 + A_2) e^{-\alpha t} = A_3 e^{-\alpha t}$$

A typical critically damped response Fig.(b).

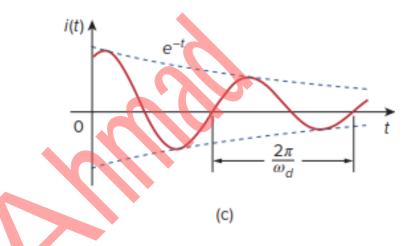
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**3. Underdamped Case** (تحت متضائلة)

$$\alpha < \omega_0$$
, i.e.  $C < 4L/R^2$   
 $\Rightarrow s_{1,2} = -\alpha \pm \sqrt{-(\omega_0^2 - \alpha^2)} = -\alpha \pm j\omega_d$   
 $j = \sqrt{-1}, \quad \omega_d = \sqrt{\omega_0^2 - \alpha^2}$ 



- $\omega_0$  is often called the undamped natural frequency,
- $\omega_{\rm d}$  is called the damped natural frequency.
- The natural response is

$$i(t) = e^{-\alpha t} (B_1 \cos \omega_d t + B_2 \sin \omega_d t)$$
  

$$B_1 = A_1 + A_2, \quad B_2 = j(A_1 - A_2)$$

- For simply,  $i(t) = e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t)$
- The response has a *time constant* of  $1/\alpha$  and a *period* of  $T = 2\pi/\omega_d$ .

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**Example 8.2.** In Fig.,  $R = 40 \Omega$ , L = 4 H, and C = 1/4 F. Calculate the characteristic roots of the circuit. Is the natural response overdamped, underdamped, or critically damped?

Solution,

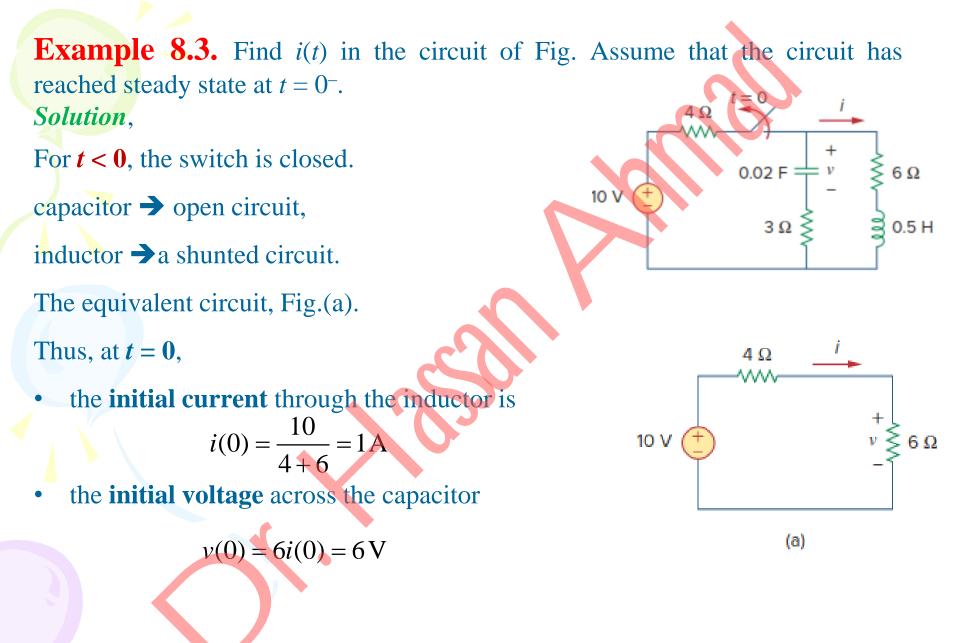
$$\alpha = \frac{R}{2L} = \frac{40}{2(4)} = 5, \quad \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{4 \times \frac{1}{4}}} = 1$$

$$\Rightarrow s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -5 \pm \sqrt{25 - 1}$$
  
$$s_1 = -0.101, \quad s_2 = -9.899$$

Since  $\alpha > \omega_0$ , we conclude that the response is overdamped.

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4Ω For t > 0, the switch is opened. The voltage source is disconnected, Fig.(b). 0.02 F 6Ω 10 V (source free series RLC circuit), 0.5 H 3Ω where the 3- $\Omega$  and 6- $\Omega$  resistors are in series when the switch is opened:  $R = 3 + 6 = 9\Omega$ The **roots** are calculated as follows: 9Ω  $\alpha = \frac{R}{2L} = \frac{9}{2(\frac{1}{2})} = 9, \quad \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{LC}}$ =100.02 F = 0.5 H  $\Rightarrow s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -9 \pm \sqrt{81 - 100}$ (b)  $=-9\pm j4.359=-\alpha\pm j\omega_{A}$  $\Rightarrow \alpha = 9, \ \omega_{1} = 4.359$ 

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### Hence, the response is underdamped ( $\alpha < \omega_0$ ); that is, $i(t) = e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t) = e^{-9t} (A_1 \cos 4.359t + A_2 \sin 4.359t)$ At t = 0, $i(0) = 1A = A_1$ But, $\frac{di}{dt}\Big|_{-} = -\frac{1}{L}(RI_0 + V_0) = -\frac{1}{L}[Ri(0) + v(0)] = -2[9(1) - 6] = -6 \text{ A/s}$ Note: $V_0 = -v(0)$ , because the polarity of *v* in Fig. (b) is opposite that in Fig. for source-free series *RLC* circuit (slid 8) Thus, $\frac{di}{dt} = \frac{d}{dt} \left[ e^{-9t} \left( A_1 \cos 4.359t + A_2 \sin 4.359t \right) \right]$ $= -9e^{-9t}(A_1\cos 4.359t + A_2\sin 4.359t) + e^{-9t}(4.359)(-A_1\sin 4.359t + A_2\cos 4.359t)$ At t = 0, $\frac{di}{dt}\Big|_{t=0} = -6 = -9(A_1 + 0) + 4.359(-0 + A_2), \text{ for } A_1 = 1 \Longrightarrow A_2 = 0.6882$ $i(t) = e^{-9t} (\cos 4.359t + 0.6882 \sin 4.359t)$ A Finally, 15 9/23/2018 Dr. Eng. Hassan Ahmad

## 8.4 Source-Free Parallel RLC Circuits

Parallel *RLC* circuits find many practical applications, notably in *communications networks and filter designs*.

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- Consider the parallel *RLC* circuit shown in Fig.
  - Assume initial inductor current  $I_0$  and initial capacitor voltage  $V_0$ ,  $i(0) = I_0 = \frac{1}{I_0} \int_{-\infty}^0 v(t) dt$ ,  $v(0) = V_0$
- Thus, applying KCL at the top node gives

$$\frac{v}{R} + \frac{1}{L} \int_{-\infty}^{0} v(\tau) d\tau + C \frac{dv}{dt} = 0$$

• Taking the *derivative* with respect to *t* and *dividing* by *C* results in

$$\frac{d^2v}{dt^2} + \frac{1}{RC}\frac{dv}{dt} + \frac{1}{LC}v = 0 \Leftrightarrow s^2 + \frac{1}{RC}s + \frac{1}{LC} = 0$$

where *s* is first derivative,  $s^2$  is second derivative. 9/23/2018 Dr. Eng. Hassan Ahmad

### • The roots of characteristic equation are

$$s^{2} + \frac{1}{RC}s + \frac{1}{LC} = 0 \Rightarrow s_{1,2} = -\frac{1}{2RC} \pm \sqrt{\left(\frac{1}{2RC}\right)^{2} - \frac{1}{LC}}$$
  
or  $s_{1,2} = -\alpha \pm \sqrt{\alpha^{2} - \omega_{0}^{2}}$   $\alpha = \frac{1}{2RC}, \quad \omega_{0} = \frac{1}{\sqrt{LC}}$ 

There are three possible solutions,

1. Overdamped Case.

$$\alpha > \omega_0$$
, i.e.  $L > 4R^2C \Rightarrow$ 

The response is  $v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$ ,  $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$ 

2. Critically Damped Case.

$$\alpha = \omega_0, i.e. \quad L = 4R^2C \Rightarrow$$
  
The response is  $v(t) = (A_1 + A_2 t)e^{-\alpha t}, \quad s_1 = s_2 = -\alpha$  (real)

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3. Underdamped Case.

$$\alpha < \omega_0$$
, i.e.  $L < 4R^2C \Rightarrow$ 

The response is

 $v(t) = (A_1 \cos \omega_d t + A_2 \sin \omega_d t)e^{-\alpha t}, \quad \omega_d = \sqrt{\omega_0^2 - \alpha^2}, \quad s_{1,2} = -\alpha \pm j\omega_d$ 

• The constants  $A_1$  and  $A_2$  in each case can be determined from the initial conditions. We need v(0) and dv(0)/dt.

$$i(0) = I_0 = \int_{-\infty}^{0} v(t)dt, \quad v(0) = V_0$$

at the top node

$$\frac{v}{R} + \frac{1}{L} \int_{-\infty}^{0} v(\tau) d\tau + C \frac{dv}{dt} = 0 \Leftrightarrow \frac{V_0}{R} + I_0 + C \frac{dv(0)}{dt}$$
  
or 
$$\frac{dv(0)}{dt} = -\frac{(V_0 + RI_0)}{RC}$$

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**Example 8.4.** In the parallel circuit of Fig., find v(t) for t > 0, assuming v(0) = 5 V, i(0) = 0, L = 1 H, and C = 10 mF. Consider these cases:  $R = 1.923 \Omega$ ,  $R = 5 \Omega$ , and  $R = 6.25 \Omega$ . Solution:  $\begin{array}{c} + \\ v \\ - \end{array} \begin{array}{c} L \\ = \end{array} \begin{array}{c} + \\ I_0 \\ - \end{array} \begin{array}{c} v \\ - \end{array} \begin{array}{c} - \\ - \end{array} \begin{array}{c} + \\ - \\ - \end{array} \end{array}$ **<u>CASE 1</u>**:  $R = 1.923 \Omega$ ,  $\alpha = \frac{1}{2RC} = \frac{1}{2 \times 1.923 \times 10 \times 10^{-3}} = 26$  $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 10 \times 10^{-3}}} = 10$ Since  $\alpha > \omega_0$  in this case, the response is overdamped. So,  $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} \Rightarrow s_1 = -2, s_2 = -50$ the corresponding response is  $v(t) = A_1 e^{-2t} + A_2 e^{-50t}$ We now apply the initial conditions to get  $A_1$  and  $A_2$ :  $v(0) = 5 = A_1 + A_2$ (1) $\frac{dv(0)}{dt} = -\frac{(V_0 + RI_0)}{RC} \Rightarrow \frac{dv(0)}{dt} = -\frac{v(0) + Ri(0)}{RC} = \frac{5 + 0}{1.923 \times 10 \times 10^{-3}} = -260$ 

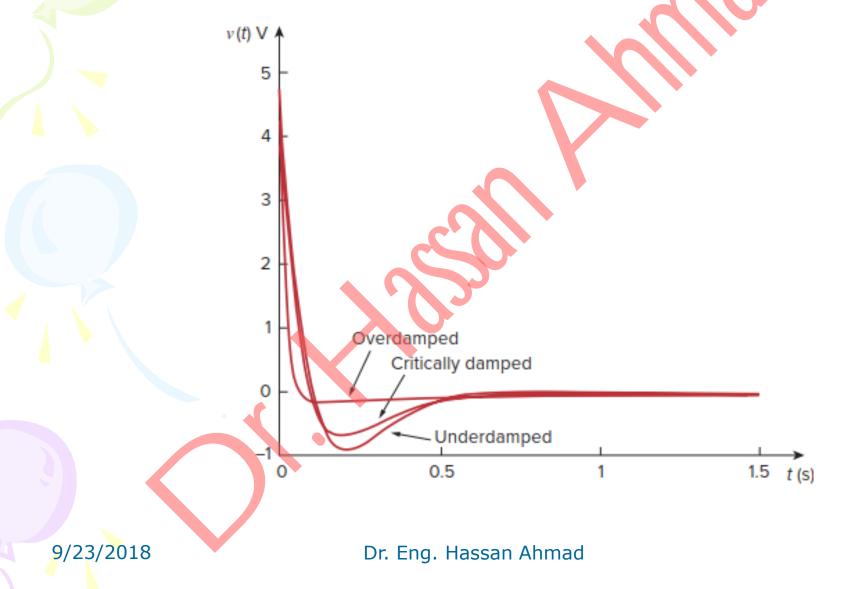
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But 
$$v(t) = A_1 e^{-2t} + A_2 e^{-50t} \Rightarrow \frac{dv}{dt} = -2A_1 e^{-2t} - 50A_2 e^{-50t}$$
  
At  $t = 0$ ,  $-260 = -2A_1 - 50A_2$  (2)  
From Eqs. (1) and (2), we obtain  $A_1 = -0.2083$  and  $A_2 = 5.208$ .  
Finally,  $v(t) = -0.2083 e^{-2t} + 5.208 e^{-50t}$   
CASE 2:  $R = 5 \Omega$ ,  
 $\alpha = \frac{1}{2RC} = \frac{1}{2 \times 5 \times 10 \times 10^{-3}} = 10$ ,  $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 10 \times 10^{-3}}} = 10$   
Since  $\alpha > \omega_0$  in this case, the response is damped. So,  
 $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} \Rightarrow s_1 = s_2 = -10$ ,  $v(t) = (A_1 + A_2 t)e^{-\alpha t} = v(t) = (A_1 + A_2 t)e^{-10t}$   
To get  $A_1$  and  $A_2$ , we apply the initial conditions:  
 $v(0) = 5 = A_1, \frac{dv(0)}{dt} = -\frac{v(0) + Ri(0)}{RC} = \frac{5+0}{5 \times 10 \times 10^{-3}} = -100$   
But,  $\frac{dv}{dt} = (-10A_1 - 10A_2 t + A_2)e^{-10t}$   
At  $t = 0$ ,  $-100 = -10A_1 + A_2 \Rightarrow A_2 = -50$   
Finally,  $v(t) = (5 - 50t)e^{-10t}$  V  
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**CASE 3:** 
$$R = 6.25 \Omega$$
,  
 $\alpha = \frac{1}{2RC} = \frac{1}{2 \times 5 \times 10 \times 10^{-3}} = 10$ ,  $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 10 \times 10^{-3}}} = 10$   
Since  $\alpha < \omega_0$  in this case, the response is underdamped. So,  
 $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} \Rightarrow s_{1,2} = -8 \pm j6 = -\alpha \pm j\omega_d \Rightarrow \omega_d = 6$   
 $v(t) = (A_1 \cos 6t + A_2 \sin 6t) e^{-8t}$   
To get  $A_1$  and  $A_2$ , we apply the initial conditions:  
 $v(0) = 5 = A_1$ ,  $\frac{dv(0)}{dt} = -\frac{v(0) + Ri(0)}{RC} = \frac{5 + 0}{6.25 \times 10 \times 10^{-3}} = -80$   
But,  $\frac{dv}{dt} = \frac{d}{dt} (A_1 \cos 6t + A_2 \sin 6t) e^{-8t}$   
 $= (-8A_1 \cos 6t - 8A_2 \sin 6t) e^{-8t}$   
At  $t = 0$ ,  $-80 = -8A_1 + 6A_2 \Rightarrow A_2 = -6.667$   
Finally,  $v(t) = (5\cos 6t + 6.667 \sin 6t) e^{-8t}$   
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Notice that by *increasing* the value of R, the *degree of damping decreases* and the *responses differ* (تختلف = تتباين). Figure plots the three cases of Example 8.4.



## 8.5 Step-Response of Series RLC Circuits

- The step response is obtained by the sudden application of a dc voltage.
- Applying KVL around the loop for t > 0,

$$L\frac{di}{dt} + Ri + v = V_s, \quad i = C\frac{dv}{dt}$$

$$\Rightarrow \frac{d^2 v}{dt^2} + \frac{R}{L}\frac{dv}{dt} + \frac{v}{LC} = \frac{V_s}{LC}$$

The solution to this Eq. has two components: the transient response  $v_t(t)$  and the steady-state response  $v_{ss}(t)$ ; that is,  $v(t) = v_t(t) + v_{ss}(t)$ 

The transient response  $v_t(t)$  is the component of the total response that dies out with time.

Therefore, the **transient response** for three cases:

 $v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$  (Ovedamped)

 $v(t) = (A_1 + A_2 t)e^{-\alpha t}$  (Critically damped)

 $v(t) = (A_1 \cos \omega_d t + A_2 \sin \omega_d t) e^{-\alpha t}$  (Underdamped)

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R

= 0

• The steady-state response is the final value of v(t).

 $v_{ss}(t) = v(\infty) = V_s$ 

• Thus, the complete solutions are:

 $v(t) = V_s + A_1 e^{s_1 t} + A_2 e^{s_2 t} \text{ (Ovedamped)}$   $v(t) = V_s + (A_1 + A_2 t) e^{-\alpha t} \text{ (Critically damped)}$  $v(t) = V_s + (A_1 \cos \omega_d t + A_2 \sin \omega_d t) e^{-\alpha t} \text{ (Underdamped)}$ 

• The values of the constants  $A_1$  and  $A_2$  are obtained from the initial conditions: v(0) and dv(0)/dt.

t = 0

**Example 8.5.** For the circuit in Fig., find v(t) and i(t) for t > 0. Consider these cases:  $R = 5 \Omega$ ,  $R = 4 \Omega$ , and  $R = 1 \Omega$ .

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Solution:

 $\underline{\textbf{CASE 1}}: R = 5 \Omega,$ 

For t < 0, the switch is closed for a long time. capacitor  $\rightarrow$  open circuit, inductor  $\rightarrow$  short circuit.

$$i(0) = \frac{24}{5+1} = 4$$
 A,  $v(0) = 1 \times i(0) = 4$  V

For t > 0, the switch is opened,  $\rightarrow 1 - \Omega$  resistor disconnected. The characteristic roots are determined as follows:

$$\alpha = \frac{R}{2L} = \frac{5}{2 \times 1} = 2.5, \quad \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 0.25}} = 2 \Longrightarrow s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -1, -4$$

Since  $\alpha > \omega_0$ , we have the overdamped natural response. The total response is therefore

$$v(t) = v_{ss} + (A_1e^{-t} + A_2e^{-4t}) = v(t) = 24 + (A_1e^{-t} + A_2e^{-4t})$$

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t = 0

0.25 F =

To find 
$$A_1$$
 and  $A_2$  using the initial conditions:  
 $v(0) = 4 = 24 + A_1 + A_2 \Rightarrow A_1 + A_2 = -20$  (1)  
 $i(0) = C \frac{dv(0)}{dt} = 4 \Rightarrow \frac{dv(0)}{dt} = \frac{4}{C} = \frac{4}{0.25} = 16$   
But,  $\frac{dv}{dt} = \frac{d}{dt} \Big[ 24 + (A_1e^{-t} + A_2e^{-4t}) \Big] = -A_1e^{-t} - 4A_2e^{-4t}$   
At  $t = 0$ ,  $\frac{dv(0)}{dt} = 16 = -A_1 - 4A_2$  (2)  
From Eqs. (1) and (2):  $A_1 = -64/3$ ,  $A_2 = 4/3$   
Finally,  $v(t) = 24 + \frac{4}{3}(-16e^{-t} + e^{-4t})$  V  
Since the inductor and capacitor are in series for  $t > 0$ , the inductor current is the

same as the capacitor current. Hence,

$$i(t) = C \frac{dv}{dt} \Longrightarrow i(t) = \frac{4}{3} (4e^{-t} - e^{-4t}) \text{ A}$$

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CASE 2: 
$$R = 4 \Omega$$
,  
For  $t < 0$ , the switch is closed for a long time.  
capacitor  $\Rightarrow$  open circuit, inductor  $\Rightarrow$  short circuit.  
 $i(0) = \frac{24}{4+1} = 4.8A$ ,  $v(0) = 1 \times i(0) = 4.8V$   
 $\alpha = \frac{R}{2L} = \frac{4}{2 \times 1} = 2$ ,  $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 0.25}} = 2 \Rightarrow s_1 = s_2 = -\alpha = -2$   
So, have the critically damped natural response. The total response is therefore  
 $v(t) = 24 + (A_1 + A_2 t)e^{-2t}$ ,  $v(0) = 4.8 = 24 + A_1 \Rightarrow A_1 = -19.2$  (1)  
 $i(0) = C \frac{dv(0)}{dt} = 4.8 \Rightarrow \frac{dv(0)}{dt} = \frac{4.8}{C} = 19.2$   
 $\frac{dv}{dt} = \frac{d}{dt} \left[ 24 + (A_1 + A_2 t)e^{-2t} \right] = (-2A_1 - 2tA_2 + A_2)e^{-2t}$   
At  $t = 0$ ,  $\frac{dv(0)}{dt} = 19.2 = -2A_1 + A_2$  (2)  
From Eqs. (1) and (2):  $A_1 = -19.2$ ,  $A_2 = -19.2$   
Finally,  $v(t) = 24 - 19.2(1+t)e^{-2t}$  V  $i(t) = C \frac{dv}{dt} \Rightarrow i(t) = (4.8e^{-t} + 9.6e^{-2t})$  A  
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**CASE 3:** 
$$R = 1 \Omega$$
,  
For  $t < 0$ , the switch is closed for a long time.  
capacitor  $\Rightarrow$  open circuit, inductor  $\Rightarrow$  short circuit.  
 $i(0) = \frac{24}{1+1} = 12 A$ ,  $v(0) = 1 \times i(0) = 12 V$   
 $\alpha = \frac{1}{2L} = \frac{1}{2 \times 1} = 0.5$ ,  $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{1 \times 0.25}} = 2$   
Since  $\alpha < \omega_0$  in this case, the response is underdamped. So,  
 $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} \Rightarrow s_{1,2} = -0.5 \pm i1.936 = -\alpha \pm j\omega_d \Rightarrow \omega_d = 1.936$   
The total response is:  $v(t) = 24 + (A_1 \cos 1.936t + A_2 \sin 1.936t)e^{-0.5t}$   
 $v(0) = 12 = 24 + A_1 \Rightarrow A_1 = -12$  (1)  
 $i(0) = C\frac{dv(0)}{dt} = 12 \Rightarrow \frac{dv(0)}{dt} = \frac{12}{C} = 48$   
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But  

$$\frac{dv}{dt} = \frac{d}{dt} \Big[ 24 + (A_1 \cos 1.936t + A_2 \sin 1.936t) e^{-0.5t} \Big]$$

$$= (-1.936A_1 \sin 1.936t + 1.936A_2 \cos 1.936t) e^{-0.5t}$$

$$- 0.5e^{-0.5t} (A_1 \cos 1.936t + A_2 \sin 1.936t)$$

At t = 0,  $\frac{dv(0)}{dt} = 48 = (-0 + 1.936A_2) - 0.5(A_1 + 0)$  (2)

From Eqs. (1) and (2):

$$A_1 = -12, \quad A_2 = 21.694$$

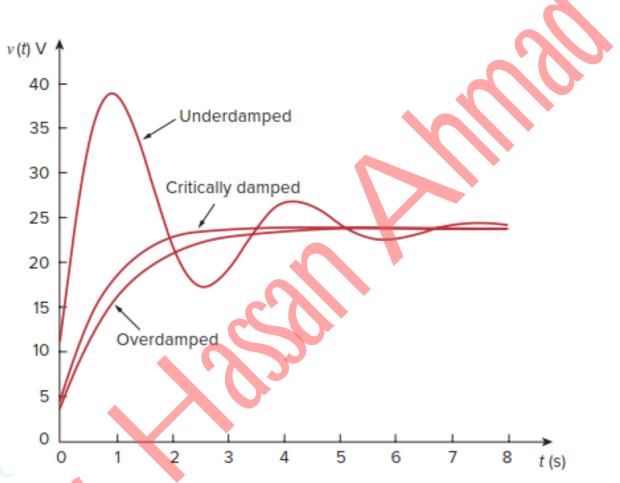
 $v(t) = 24 + (21.694 \sin 1.936t - 12 \cos 1.936t) e^{-0.5t}$  V Finally,

The inductor current is:

$$i(t) = C \frac{dv}{dt} \Rightarrow i(t) = (3.1 \sin 1.936t + 12 \cos 1.936t) e^{-0.5t}$$
 A

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Figure plots the responses for the three cases.



From this figure, we observe that the critically damped response approaches the step input of 24 V the fastest.

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## **8.6 Step-Response of Parallel RLC Circuits**

- The step response is obtained by the sudden application of a dc current.
  - Applying KCL at the top node for t > 0,

 $\frac{v}{D} + i + C \frac{dv}{L} = I_s$ 

$$\frac{v}{R} + i + C\frac{dv}{dt} = I_s$$
with  $v = L\frac{di}{dt} \Rightarrow \frac{d^2i}{dt^2} + \frac{1}{RC}\frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC}$ 

The complete solution consists of the transient response  $i_t(t)$  and the steady-state response  $i_{ss}(t)$ ; that is,  $i(t) = i_{t}(t) + i_{s}(t)$ 

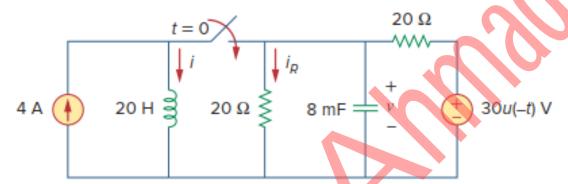
The final value of the current through the inductor is the same as the source current  $I_s$ . Thus,  $i(t) = I_{s} + A_{1}e^{s_{1}t} + A_{2}e^{s_{2}t}$  (Ovedamped)

 $i(t) = I_s + (A_1 + A_2 t)e^{-\alpha t}$  (Critically damped)

 $i(t) = I_s + (A_1 \cos \omega_d t + A_2 \sin \omega_d t) e^{-\alpha t}$  (Underdamped)

The constants A1 and A2 in each case can be determined from the initial conditions for i and di/dt. 9/23/2018 31 Dr. Eng. Hassan Ahmad

**Example 8.6.** In the circuit of Fig., find i(t) and  $i_R(t)$  for t > 0.



### Solution:

For t < 0, the switch is open, and the circuit is partitioned into two independent subcircuits, Fig.(a).

$$4 \text{ A} \underbrace{20 \text{ H}}_{\text{(a)}} \underbrace{20 \text{ H}}_{\text{(a)}} \underbrace{20 \text{ \Omega}}_{\text{(a)}} \underbrace{8 \text{ mF}}_{\text{(a)}} \underbrace{+}_{\text{(a)}} \underbrace{30u(-t) \text{ V}}_{\text{(a)}}$$

- The 4-A current flows through the inductor, so that i(0) = 4 A
- $t < 0 \rightarrow 30u(-t) = 30; t > 0 \rightarrow 30u(-t) = 0$ , the voltage source is operative for t < 0.

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- The capacitor acts like an open circuit, and  $v_{(8mF)} = v_{(20\Omega)}$ , Fig.(b).
- By VDR on Fig.(b)., the initial capacitor voltage (t =0) is

$$v(0) = \frac{20}{20 + 20} (30) = 15 \,\mathrm{V}$$

For t > 0, the switch is closed, and we have a parallel *RLC* circuit with a current source, Fig.(c).

•  $t > 0 \Rightarrow 30u(-t) = 0$ , the voltage source acts like a *short-circuit*, Fig.(d). Thus,  $R = 20 \parallel 20 = 10 \Omega$ .

$$\alpha = \frac{1}{2RC} = \frac{1}{2 \times 10 \times 8 \times 10^{-3}} = 6.25, \quad \omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{20 \times 8 \times 10^{-3}}} = 2.5$$
$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2} = -6.25 \pm 5.7282 \equiv s_1 = -11.978, \quad s_2 = -0.5218$$

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20 Ω

**20 Ω** 

8 mF

30u(-t) V

30u(--t) V

20 Ω

20 Н 쥑

20 H

4 A

4 A

4 A

20 Ω

(b)

20 Ω Š

(c)

20 H 🚽

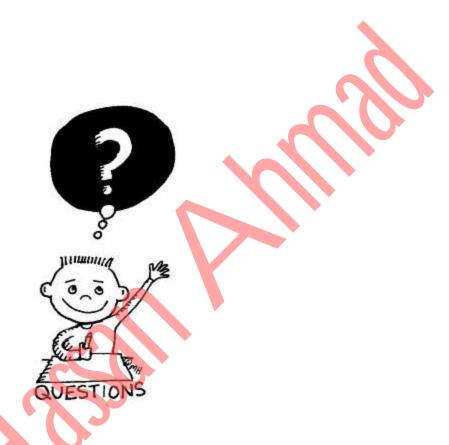
i<sub>R</sub>

**20 Ω** 

(đ)

8 mF =

Since 
$$a > \omega_0$$
 we have the overdamped case. Hence,  
 $i(t) = I_s + A_1 e^{s_1 t} + A_2 e^{s_2 t} = 4 + A_1 e^{-11.978t} + A_2 e^{-0.5218t}$   
At  $t = 0$ ,  $\Rightarrow i(0) = 4 + A_1 + A_2 = 4 \Rightarrow A_2 = -A_1$  (1)  
But  $\frac{di}{dt} = \frac{d}{dt} \left( 4 + A_1 e^{-11.978t} + A_2 e^{-0.5218t} \right) = -11.978A_1 e^{-41.978t} - 0.5218A_2 e^{-0.5218t}$   
so that at  $t = 0$ ,  $\frac{di(0)}{dt} = -11.978A_1 - 0.5218A_2$   
But  $v(t) = L\frac{di(t)}{dt} \Rightarrow v(0) = L\frac{di(0)}{dt} = 15 \Rightarrow \frac{di(0)}{dt} = \frac{15}{L} = \frac{15}{20} = 0.75$   
Thus,  $-11.978A_1 - 0.5218A_2 = 0.75$  (2)  
From Eqs.(1) and (2):  $A_2 = 0.0655$ ,  $A_1 = -0.0655$   
The complete solution is as  $i(t) = 4 + 0.0655(e^{-0.5218t} - e^{-11.978t})$  A  
 $i_R(t) = \frac{v(t)}{20} = \frac{1}{20}L\frac{di}{dt} = i(t) = 0.785e^{-11.978t} - 0.0342e^{-0.5218t}$  A  
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## The end of chapter 8

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